Optimal Transport and Machine Learning

November 19, 2021

1 Introductory notes

Monge 1781.

Suppose μ and ν are two measures on $\mathbb{R}^d, d \ge 1$. Consider any function $T : \mathbb{R}^d \to \mathbb{R}^d$ that push forward μ to ν . Suppose $X \sim \mu$, then $y = T(X) \sim \nu$.

Problem 1.1. Monge's problem. What is the infimum of

$$\int ||T(x) - x|| \mu(dx) = \mathbb{E}[||T(X) - X||]$$

over the set of all push forwards of μ to $\nu?$

Monge's idea: move dirt to castle.

$$Vol(Dirt) = Vol(Castle)$$

Every x in Dirt should be carried to y. We wish to have minimum work possible. Two points are ||y - x||.

Summing up all the things,

$$\inf \int ||T(x) - x|| \mu(dx)$$

This is a hard problem.

Consider if we just take $\mu = \delta_0$, and $\nu = Ber(1/2)$.

The set of pushforwards is not nice (not convex, smooth, ...)

How to generalize? Monge is mapping cost as ||T(x) - x|| = cost of transporting.

Why not use $||T(x) - x||^2$? Why note use $||T(x) - x||^{40}$?

Define a cost function $c : \mathbb{R}^d \times \mathbb{R}^d \to [0, \infty]$ Generalized Monge Problem (MP): find

 $\inf \int c(x,T(x))\mu(dx)$

among all pushforwards of μ to ν .

Kantorovich's relaxation: without enforcing existence of mapping.

Coupling Given μ and ν , a coupling of (μ, ν) refers to any joint distribution on $\mathbb{R}^d \times \mathbb{R}^d$,

such that if $(X, y) \sim \rho$, then $X \sim \mu$, $Y \sim \nu$.

- **Example 1.2.** Suppose T is a pushforward from μ to ν , then (X, T(X)) where $X \sim \mu$ is a coupling of (μ, ν) .
- **Example 1.3.** Suppose $X \sim \mu$ independent of $Y \sim \nu$, then $(X, Y) \sim \mu \otimes \nu$ is a coupling of (μ, ν) .

Let $\pi(\mu, \nu)$ be the set of couplings, then $\pi(\mu, \nu) \neq \emptyset$.

Problem 1.4. Kantorovich Problem (KP).

Find

$$\inf_{\pi\in\Pi(\mu,\nu)}\int c(x,y)d\pi$$

E.g.

$$\inf_{\pi\in\Pi(\mu,\nu)}\int ||x-y||^2\pi(dxdy)$$

Advantage

1. $\pi(\mu, \nu)$ is a non-empty convex set.

2. The function being optimized is affine.

3. KP is a linear programming problem.

In details:

1. $\pi(\mu, \nu)$ is convex. How to verify $\pi \in P(\mathbb{R}^d \times \mathbb{R}^d)$ is an element in $\Pi(\mu, \nu)$? Take some $A \subseteq \mathbb{R}^d$, sample $(X, Y) \sim \Pi$, check:

$$P_{\Pi}(x \in A) = \mu(A), P_{\Pi}(y \in A) = \nu(A), \forall A.$$

Alternatively, consider f to be a bounded function,

$$\begin{split} c^f_x &:= \int f(x) d\mu, \quad c^f_y := \int f(y) d\nu \\ \bar{f}(x,y) &:= f(x), \quad \underline{\mathbf{f}}(\mathbf{x},\mathbf{y}) {:=} \mathbf{f}(\mathbf{y}) \end{split}$$

Check

$$\begin{cases} \mathbb{E}_{\Pi}[\bar{f}] = \int \bar{f}(x, y) d\pi = c_x^f \\ \mathbb{E}_{\Pi}[\underline{f}] = \int \underline{f}(\mathbf{x}, \mathbf{y}) d\pi = c_y^f \end{cases}$$

Intersecting $P(\mathbb{R}^d \times \mathbb{R}^d)$.

2. The function is linear in π

How are MP and KP related?

What is the value of problem?

Is inf = min? Does solution exist?

Is the minimizer unique?

If so, how does the optimizer look like? Will focus mostly on $c(x, y) = ||y - x||^2$.

1.1 When is the infimum achieved?

Weienstrass Theorem.

Theorem 1.5. Suppose the cost function c is continuous, then KP admits a solution. That is, there is some coupling $\pi^* \in \Pi(\mu, \nu)$ that attains infinum.

Proof. Depends on this basic lemma.

Lemma 1.6. If f is a real-valued continuous function on a compact metric space X, then \exists some $x^* \in X$ such that

$$f(x^*) = \min_{x \in X} f(x)$$

Proof. Let $l = \inf_x f(x)$. Assume $l > -\infty$. For every $n \ge 1, \exists$ some x_n s.t.

$$l \le f(x_n) \le l + \frac{1}{n}$$

Then sequence $(x_n, n \ge 1)$ has a converging subsequence.

$$x_{n_k} \to x^*$$

What is $f(x^*)$?

$$f(x^*) = \lim_{k \to \infty} f(x_{n_k}) \le \lim_{n \to \infty} (l + \frac{1}{n_k}) = l = \inf_x f(x)$$

Metrics on probability measures. $P(\mathbb{R}^n)$

Definition 1.7. For a sequence $(\rho_k, k \ge 1)$ in $P(\mathbb{R}^n)$, say $\lim_{k \to \rho_k} = \rho$ if

$$\lim \int f d\rho_k = \int f d\rho, \text{ for all bounded continuous functions } f : \mathbb{R}^n \to \mathbb{R}$$

"Weak convergence of probability measures" There is a metric that gives us this weak convergence.

$$d(\rho_0, \rho_1) = \sup_{f \in BL} \left| \int f d\rho_0 - \int f d\rho_1 \right|$$

BL is the set of all functions bounded (B) by 1 and is Lipschitz (L). $|f(x)| \le 1$, $|f(x) - f(y)| \le ||x - y||$.

Theorem 1.8. For any μ and ν , the set

 $\Pi(\mu,\nu)$ is compact in the topology of weak convergence.

Proof follows from Prokhonor's Theorem. We can verify from this theorem (for stating out what is weak convergence).

Thus, $\Pi(\mu, \nu)$ is a compact metric space.

The entire $P(\mathbb{R}^n)$ cannot be compact.

$$\rho_k = \delta_k, \lim_{k \to \infty} \int f(x) d\rho_k = f(k)$$

Proof. [Sketch]

Assume μ, ν are compactly supported. It means there exist a big compact ball in \mathbb{R}^d that the entire measures live in this compact ball.

Every element in $\Pi(\mu, \nu)$ must be supported in some big enough box $[-a, a]^{2d}$. On that box, the continuous cost function c is also bounded. Thus,

$$\pi\in\Pi(\mu,\nu)\to\int c(x,y)d\pi$$

is a continuous function.

By Weienstrass, $\exists \pi^*$,

$$\inf_{\pi\in\Pi(\mu,\nu)}\int cd\pi = \int c(x,y)d\pi^*.$$

1.2 Linear Algebra

Suppose

$$\mu = \frac{1}{n} \sum_{i=1}^{n} \delta_{x_i}$$
$$\nu = \frac{1}{n} \sum_{j=1}^{n} \delta_{y_j}$$

What is $\Pi(\mu, \nu)$? Given by Doubly-Stochastic matrices (DS matrices).

Definition 1.9. $A_{n \times n} = (a_{ij})$ is DS if

1. $a_{ij} \ge 0$ 2. Row sum = 1 3. Col sum = 1

 $\begin{array}{l} \frac{1}{n}A \iff \Pi(\mu,\nu). \\ P(X=x_i,Y=y_j). \\ \text{Special case: Permutation matrices. 1-2, 2-1, 3-3.} \\ \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ (\frac{1}{n}A_{\pi}) \iff Push \ Forwards \end{array}$

KP in Linear Algebra.

$$C = (c_{ij}), \ c_{ij} = c(x_i, y_j)$$
$$\frac{1}{n} \langle A, C \rangle = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^n a_{ij} c_{ij}$$

KP becomes

$$\inf_{A \; over \; all \; DS \; matrices \; n \times n} \langle A, C \rangle$$

Fact 1.10. This minimum exists and is achieved at some permutation matrix.

$$(KP) = (MP)$$
$$= \sum p_i \delta_{x_i}, \nu = \sum q_j \delta_{y_j}$$

Find $\Pi(\mu, \nu)$ is some set of matrices

 μ

$$\inf_A \langle C, A \rangle$$

is a Linear programming problem.

2 Convex functions and their duals

2.1 Review

MK OT problem

$$c(x,y) = ||y - x||^2$$

Given μ, ν on \mathbb{R}^d

$$\pi(\mu,\nu) - set \ of \ couplings$$

KP is

$$\inf_{\pi \in \Pi(\mu,\nu)} \int ||y-x||^2 d\pi$$

If this infimum is given by a coupling $(X, T(X)), X \sim \mu, T(X) \sim \nu$. We say KP admits a Monge solution.

Example 2.1. $\mu = \mathcal{N}(0, I)$ on \mathbb{R}^d . $\nu = \mathcal{N}(w, I)$ on \mathbb{R}^d . What is the solution of KP?

The solution is a shift that

$$T(x) = x + w$$

Here, (Z, T(Z)) is the optimal solution to (KP).

τ

How do I argue this? Brenier Theorem.

The reason is $T(X) = \nabla f(x), f(x) = \frac{1}{2}||x + w||^2$. If you can find a convex function gradient, this must be the optimal.

If μ has a density (absolutely continuous), no matter what ν is, there always exists some convex function f, ∇f pushforwards μ to ν .

Weak convergence of measures $(\rho_k, k \ge 1)$ seq. in $P(\mathbb{R}^d)$

Say $\rho_k \to \rho$ if

$$\int f d\rho_k = \int f d\rho$$

For every bounded continuous function $f : \mathbb{R}^n \to \mathbb{R}$.

Example 2.2. From [0, 1], draw k partitions.

$$\rho_k = Unif[\frac{i}{k}, i = 1, 2, ..., k]$$

When $k \to \infty$,

$$\rho_k \to \rho = Unif[0,1]$$

Why is this true? Take any f bounded and continuous.

$$\int f d\rho_k = \sum f(i/k) \frac{1}{n} = \frac{1}{n} \sum_{i=1}^n f(i/k) =_{k \to \infty} \int_0^1 f(x) dx = \int f(x) \rho(dx)$$

Even $X_1, \ldots, X_k \sim_{iid} Unif[0, 1].$

$$\frac{1}{k} \sum_{i=1}^{k} \delta_{X_i} \to_{a.s.}^{k \to \infty} Unif[0,1]$$

2.2 Convex Analysis

Definition 2.3. $f : \mathbb{R}^d \to \mathbb{R} \cup \{+\infty\}$ is called convex if for any $x, y \in \mathbb{R}^d$, any 0 < t < 1

$$f((1-t)x + ty) \le (1-t)f(x) + tf(y)$$

And strictly convex if

$$f((1-t)x + ty) < (1-t)f(x) + tf(y)$$

Definition 2.4. f is concave if -f is convex.

Definition 2.5. A is a convex set, if $x, y \in A$, then

$$\{(1-t)x + ty, 0 \le t \le 1\} \subseteq A.$$

Example 2.6. $x \in \mathbb{R}^d$, $f(x) = ||x||^2$ strictly convex.

Example 2.7. If $f(x) = \sum_{i} |x_i|$. This is convex but not strictly convex.

Example 2.8. $f(x) = ||x||_p^p, p > 1$, is strictly convex. If p < 1, concave function.

Example 2.9. $f(x) = \log\left(\sum_{i=1}^{d} e^{X_i}\right), x \in \mathbb{R}^d$. Verify this is convex. Show the Hessian.

Convex functions could be infinity somewhere

Example 2.10.
$$f(x) = \begin{cases} -\log x & x > 0 \\ +\infty & x \le 0 \end{cases}$$

This is also a convex function.

Domain of $f = \{x \in \mathbb{R}^d : f(x) < +\infty\} \neq \emptyset$.

2.2.1 How convex sets related to convex function

Suppose Ω is a convex set.

Convex indicator function: $f(x) = \begin{cases} 0, & x \in \Omega \\ +\infty, & x \notin \Omega \end{cases}$ Verify that f is convex function if Ω is convex set. Conversely, convex functions to convex sets. Suppose f is a Convex function. Consider the epigraph of f

$$epi(f) = \Omega = \left\{ (x, t) \in \mathbb{R}^{d+1} : t \ge f(x) \right\}$$

f is convex function if and only if the epigraph is convex set.

Properties

1. Closed under supremum.

$$\{f_{\alpha}, \alpha \in I\}$$

$$f_{\alpha} \to \mathbb{R} \cup \{\infty\}$$

is convex, then so is

$$f(x) = \sup_{\alpha} f_{\alpha}(x).$$

x, y, 0 < t < 1

$$f_{\alpha}((1-t)x + ty) \le (1-t)f_{\alpha}(x) + tf_{\alpha}(y)$$

Then

$$\sup_{\alpha} f_{\alpha}((1-t)x + ty) \le \sup_{\alpha} [(1-t)f_{\alpha}(x) + tf_{\alpha}(y)]$$

2. Convex functions may not be always differentiable, or continuous.

1

$$f(x) = \begin{cases} x^2, & -1 < x < \\ 2, & x = \pm 1 \\ \infty, & |x| > 1 \end{cases}$$

This function is convex but not continuous at the boundary. It is locally Lipschitz in the interior(dom(f))It is differentiable almost everywhere inside interior(dom(f)). It is "double differentiable" a.s. We are only going to consider a convex function that are lower semicontinuous

$$(x_k) \to x$$

 $\lim f(x_k) \ge f(x) \iff epi(f) \text{ is closed.}$

3. Every convex lower semicontinuous function can be written in the following representation

$$\exists (a_{\alpha} \in \mathbb{R}^{d}, b_{\alpha} \in \mathbb{R}, \alpha \in I)$$

such that

$$f(x) = \sup_{\alpha} \left[\underbrace{\langle a_{\alpha}, x \rangle + b_{\alpha}}_{affine \ in \ x} \right]$$

This is a dual representation of f.

Definition 2.11. Let $f : \mathbb{R}^d \to \overline{\mathbb{R}}$. Define Legendre transform (convex conjugate) of f,

$$f^*(y) = \sup_{x \in \mathbb{R}^d} \left[\langle x, y \rangle - f(x) \right] \to convex \ l.s.c \ function$$

Double star?

$$f^{**}(x) = \sup_{y \in \mathbb{R}^d} \left[\langle x, y \rangle - f^*(y) \right]$$

 $f^{**} = f \iff f \ is \ convex + lsc$

Otherwise, f^{**} is called "convex evelope".

Example 2.12. $f(x) = \frac{1}{2}||x||^2$.

$$f^*(x) = \sup_{x} \left[\langle x, y \rangle - \frac{1}{2} ||x||^2 \right]$$

Let $g(x) = \langle x, y \rangle - \frac{1}{2} ||x||^2$

$$\nabla g(x) = y - x = 0$$

Therefore,

$$f^*(x) = \frac{1}{2}||y||^2 = f(y)$$

 $f = f^*$ is self-dual.

Example 2.13. $f(x) = \begin{cases} -\log x, & x > 0 \\ +\infty, & x \le 0 \end{cases}$ $f^*(y) = \begin{cases} -1 - \log |y|, & y < 0 \\ +\infty, & y \ge 0 \end{cases}$

What if we have a f^{**} ? Since f(x) is convex and lsc, we get back f(x).

Example 2.14. $\Omega = [-1,1]^d$, $f(x) = \begin{cases} 0, & x \in \Omega \\ +\infty, & x \notin \Omega \end{cases}$

$$f^*(y) = \sup_{x \in \mathbb{R}^d} [\langle x, y \rangle - f(x)]$$
$$= \sup_{x \in \Omega} [\langle x, y \rangle]$$
$$= \sup_{x \in [-1,1]^d} \sum_{i=1}^d x_i y_i$$
$$= ||y||_1$$

$$\begin{split} f^{**}(x) &= \sup_{y \in \mathbb{R}^d} \left[\langle x, y \rangle - f^*(y) \right] \\ &= \sup_{y \in \mathbb{R}^d} \left[\langle x, y \rangle - ||y||_1 \right] \\ &= \begin{cases} +\infty, & \text{if } x \notin \Omega \\ 0, & \text{if } x \in \Omega \end{cases} \end{split}$$

Interestingly, if $\Omega = (-1, 1)^d$, $f^{**}(x) = [-1, 1]^d$.

Theorem 2.15. Suppose f and f^* are convex and differentiable over \mathbb{R}^d . (Differentiable implies lsc).

- 1. $f(x) + f^*(y) \ge \langle x, y \rangle$ for all $x, y \in \mathbb{R}^d$, with = holds if and only if $y = \nabla f(x)$.
- 2. $\nabla f : \mathbb{R}^d \to \mathbb{R}^d, \nabla f^* : \mathbb{R}^d \to \mathbb{R}^d$ are inverse of one another.

$$\nabla f(\nabla f^*(y)) = y$$

$$\nabla f^*(\nabla f(x)) = x$$

Proof. Idea of the proof. (1)

$$f^*(y) = \sup_x \left[\langle x, y \rangle - f(x) \right] \ge \langle x, y \rangle - f(x)$$
$$f(x) + f^*(y) \ge \langle x, y \rangle$$

Where the supremum is achieved? FO condition:

$$y = \nabla f(x)$$

$$f^*(y) = \langle x, y \rangle - f(x), y = \nabla f(x).$$

(2) ∇f and ∇f^* are inverse of each other. Very interesting fact. Start from (1). Replace f by f^* , and f^* by $f^{**} = f$.

$$\begin{aligned} f(x) &= \sup_{y} \left[\langle x, y \rangle - f^{*}(y) \right], maximized \ when \ x = \nabla f^{*}(y). \\ f(x) &= \langle x.y \rangle - f^{*}(y), x = \nabla f^{*}(y) \\ (1), \ \langle x, \nabla f(x) \rangle - f^{*}(\nabla f(x)) = f(x). \end{aligned}$$

2.3 Weak Convergence distances

BL denotes bounded Lipschitz that $||f||_{\infty} \leq 1, Lip-1.$

$$\sup_{f\in BL} \left| \int f d\mu - \int f d\nu \right|$$

Consider

From

$$W_2^2(\mu,\nu) = \inf_{\Pi(\mu,\nu)} \int ||y-x||^2 d\pi = dual \ representation$$

Then we can see Brenier's Theorem.

$$\nabla f: \mu \to \nu$$

 $\nabla f^*: \nu \to \mu$

3 Kantorovich Duality

3.1 Review of Convex functions

 $f:\mathbb{R}^d\to\mathbb{R}\cup\{\infty\},$ convex and lower semicontinuous. We can define dual/conjugate with

$$f^*(y) = \sup_{x \in \mathbb{R}^d} \left[\langle x, y \rangle - f(x) \right]$$

1.
$$\forall x, y, f(x) + f^*(y) - \langle x, y \rangle \ge 0, = 0$$
 iff $y = \nabla f(x)$ or $x = \nabla f^*(y)$
2. $\nabla f(\nabla f^*(x)) = x$

Example 3.1. d = 1. $f(x) = \begin{cases} x \log x, & x \ge 0 \\ \infty, & x < 0 \end{cases}$. cx lsc.

Check convexity,

$$f'(x) = 1 + \log x$$

Check lsc.

$$\lim_{x \to 0} x \log x = 0$$

Let $y = 1 + \log x$, $x = e^{y-1}$.

$$(f^*)'(y) = e^{y-1}$$

$$f^*(y) = \sup_{x} [xy - x\log x] = \sup_{x \ge 0} [xy - x\log x] = e^{y-1}$$

Domain of f^* is \mathbb{R} and $Domain(f) = [0, \infty)$. Another observation Take f cx and lsc

$$\inf_{x \in \mathbb{R}^d} f(x) = -\sup_{x \in \mathbb{R}^d} \left[-f(x) \right]$$
$$= -\sup_{x} \left[\langle x, 0 \rangle - f(x) \right]$$
$$= -f^*(0)$$

The infimum is attained via checking the dual at 0. Let x^* is the unique minimizer,

$$\nabla f(x^*) = 0, x^* = \nabla f^*(0)$$
$$x^* = \nabla f^*(0)$$

3.2 Kantorovich Duality

Very similar to 3.1, but in infinity dimension.

Consider the optimal transport problem with a continuous cost $c : \mathbb{R}^d \times \mathbb{R}^d \to [0, \infty]$.

For $\pi \in \Pi(\mu, \nu)$,

$$I(\pi) = \int c(x, y) d\pi$$

cost of transport using the plan π . We wish to find out

$$\inf_{\pi \in \Pi} I(\pi)$$

This is doing in the space of functions/measures.

For any function $\varphi \in L^1(\mu)$ and $\psi \in L^1(\nu)$. L^1 means that the integral is finite.

In this case, $\int |\varphi| d\mu < \infty$.

Define

$$J(\varphi,\psi) = \int \varphi(x) d\mu + \int \psi(y) d\nu$$

Let $\Phi = \{\varphi, \psi \text{ such that } \varphi(x) + \psi(y) \le c(x, y), \forall x, y\}.$

Theorem 3.2. (Kantorovich Duality)

$$\inf_{\pi\in\Pi(\mu,\nu)}I(\pi)=\sup_{\Phi}J(\varphi,\psi).$$

The supremum above does not change if we restrict φ, ψ to be bounded continuous functions.

One side is obvious.

Suppose $\pi \in \Pi(\mu, \nu)$. Take any φ, ψ satisfying $\varphi(x) + \psi(y) \leq c(x, y), \forall x, y$.

$$c(x,y) \ge \varphi(x) + \psi(y)$$

$$\begin{split} I(\pi) &= \int c(x,y) \geq \int \varphi(x) d\pi + \int \psi(y) d\pi \\ &= \int \varphi(x) d\mu + \int \psi(y) d\nu \\ &\geq \sup_{\Phi} \left[J(\varphi,\psi) \right] \end{split}$$

Therefore,

$$\inf_{\pi\in\Pi} I(\pi) \geq \sup_{\Phi} \left[J(\varphi,\psi) \right]$$

K-duality "=" means there is no duality gap. Minimax inequalities.

3.2.1 Quadratic Cost

$$c(x,y) = \frac{1}{2} ||y - x||^2$$

= $\frac{1}{x} ||x||^2 + \frac{1}{2} ||y||^2 - \langle x, y \rangle$

$$\begin{split} I(\pi) &= \int c(x,y) d\pi = \frac{1}{2} \int ||x||^2 d\pi + \frac{1}{2} \int ||y||^2 d\pi - \int \langle x,y \rangle \, d\pi \\ &= \frac{1}{2} \int ||x||^2 d\mu + \frac{1}{2} \int ||y||^2 d\nu - \int \langle x,y \rangle \, d\pi \\ &\inf_{\Pi(\mu,\nu)} I(\pi) = \frac{1}{2} \mathbb{E}_{\mu} ||x||^2 + \frac{1}{2} \mathbb{E}_{\nu} ||y||^2 - \sup_{\pi} \int \langle x,y \rangle \, d\pi \end{split}$$

We give this a name Wasserstein-2 distance between μ and ν that

$$W_2^2(\mu, \nu) = \inf_{\Pi(\mu, \nu)} I(\pi)$$

Fact. $W_2(\mu,\nu)$ is a metric on $P(\mathbb{R}^d)$ with finite second moment.

By K-duality,

$$W_2^2(\mu,\nu) = \inf_{\Pi(\mu,\nu)} I(\pi) = \frac{1}{2} \mathbb{E}_{\mu} ||x||^2 + \frac{1}{2} \mathbb{E}_{\nu} ||y||^2 - \sup_{\Pi(\mu,\nu)} \int \langle x,y \rangle \, d\pi$$
$$= \sup_{\Phi} \left[\int \varphi d\mu + \int \psi(y) d\nu \right]$$

$$\sup_{\Pi(\mu,\nu)} \int \langle x,y \rangle \, d\pi = \inf_{\Phi} \left[\frac{1}{2} \int \left(\underbrace{||x||^2 - \varphi(x)}_{f(x)} \right) d\mu + \frac{1}{2} \int \left(\underbrace{||y||^2 - \psi(y)}_{g(y)} \right) d\nu \right]$$

Constraints here is

$$\varphi(x) + \psi(y) \le \frac{1}{2} ||y - x||^2 = \frac{1}{2} ||y||^2 + \frac{1}{2} ||x||^2 - \langle x, y \rangle$$
$$f(x) + g(y) \ge \langle x, y \rangle$$

$$\sup_{\Pi(\mu,\nu)} \int \langle x,y \rangle \, d\pi = \inf_{f(x)+g(y) \ge \langle x,y \rangle, \forall x,y} \left[\int f(x) d\mu + \int g(y) d\nu \right]$$

Are their such functions satisfy this constraint??? Yes! Recall that

$$f(x) + f^*(y) - \langle x, y \rangle \ge 0$$

Now fix f,

$$\inf \int f(y) d\nu, g(y) \ge \langle x, y \rangle - f(x), \forall x$$

$$g(y) \ge \sup_{x} \left[\langle x, y \rangle - f(x) \right] = f^*(y)$$

Therefore,

$$\inf \int g(y)d\nu = \int f^*(y)d\nu$$

$$\sup_{\Pi(\mu,\nu)} \int \langle x,y \rangle \, d\pi = \inf_{\substack{f(x)+g(y) \ge \langle x,y \rangle, \forall x,y}} \left[\int f(x) d\mu + \int g(y) d\nu \right]$$
$$= \inf_{f \in L^1(\mu)} \left[\int f(x) d\mu + \int f^*(y) d\nu \right]$$

Fix f^* , and we optimize over f.

$$= \inf_{f} \left[\int f^{**}(x) d\mu + \int f^{*}(y) d\nu \right]$$
$$\sup_{\pi} \int \langle x, y \rangle d\pi = \inf_{f \ cx, lsc} \left[\int f(x) d\mu + \int f^{*}(y) d\nu \right]$$

This trick called **double convexification trick**.

Ultimate form of W2 distance

$$\frac{1}{2}W_2^2(\mu,\nu) = \frac{1}{2}\left[\int ||x||^2 d\mu + \int ||y||^2 d\nu\right] - \inf_{f \ cx \ lsc.}\left[\int f(x)d\mu + \int f^*(y)d\nu\right]$$

3.2.2 Other cost functions

Earth Move Distance: Wasserstein-1 distance

$$c(x,y) = ||y - x||$$

$$W_1(\mu,\nu) = \inf_{\Pi(\mu,\nu)} \int ||y-x|| d\pi$$

What is it dual representation? K-duality says

$$= \sup_{f \ Lip} \left| \int f d\mu - \int f d\nu \right|$$

Lipschitz-1 means

$$|f(x) - f(y)| \le ||x - y||$$

Recall There is a metric for weak convergence given by

$$d(\mu, \nu) := \sup_{f \in BL} \left| \int f d\mu - \int f d\nu \right|$$

If we have

$$\lim_{n \to \infty} d(\mu_n, \nu) = 0$$

means that (μ_n) weakly converges to ν .

$$d(\mu,\nu) \le W_1(\mu,\nu)$$

 W_1 gives a stronger topology.

Consider only probability measures that supported on a compact set. In this case, these topologies are equivalent.

3.2.3 Wasserstein-p Distance

$$W_p(\mu,\nu) = \inf_{\Pi(\mu,\nu)} \int ||x-y||^p d\pi$$

This is Wasserstein p metric. If $p \neq 2$, there is no convenience reformulation of K-duality.

 $p = \infty$

$$W_{\infty} = \inf_{\Pi(\mu,\nu)} \underbrace{ess \sup_{\pi} \left(||y-x|| \right)}_{\inf\{a > 0:\pi(||y-x|| \le a) = 1\}}$$

p = 0 This is the total variation.

$$c(x,y) = \mathbf{1} \{ x \neq y \} = \begin{cases} 1, & \text{if } x \neq y \\ 0, & \text{otherwise} \end{cases}$$

K-duality still holds and can be reformulated as

$$\begin{aligned} ||\mu - \nu||_{TV} &= \inf_{\pi \in \Pi(\mu,\nu)} \pi(x \neq y) \\ &= \sup_{A \ Borel} |\mu(A) - \nu(A)| \end{aligned}$$

Strassen's Theorem (1950).

Proof. Idea of proof of K-duality

$$\inf_{\pi} I(\pi) = \sup_{\Phi} \left[\int \varphi d\mu + \int \psi d\nu \right]$$

Consider indicator function of $\Pi(\mu, \nu)$.

 $M_{+} = space \ of \ nonnegative \ measures$

$$F(\pi) = \begin{cases} 0, & \text{if } \pi \in \Pi(\mu, \nu) \\ +\infty, & \pi \in M_+, \pi \notin \Pi(\mu, \nu) \end{cases}$$

Lemma 3.3. Here we have

Proof.

$$F(\pi) = \sup_{\varphi \in L^1(\mu), \psi \in L^1(\nu)} \left[\int \varphi d\mu + \int \psi d\nu - \int (\varphi(x) + \psi(y)) d\pi \right]$$

Proof. Take $\pi \notin \Pi(\mu, \nu)$. Assume $(x, y) \sim \pi$, then $x \sim \mu' \neq \mu$. There is some φ (bounded cont.) s.t.

$$\int \varphi(x) d\mu > \int \psi(x) d\pi$$

 $\lambda > 0,$

$$\lambda[\int \varphi(x)d\mu - \int \varphi(x)d\pi] > 0$$

Let $\lambda \to \infty$. Thus, there exists something let

$$F(\pi) = \infty$$

If $\pi \in \Pi$, we can construct

$$F(\pi) = 0$$

Proof. Back to the previous proof

$$I(\pi) + F(\pi) = \inf_{\pi} I(\pi) = \sup_{\Phi} \left[\int \varphi d\mu + \int \psi d\nu \right]$$

$$\begin{split} \inf_{\Pi} I(\pi) &= \inf_{\pi \in M_{+}} \left[I(\pi) + F(\pi) \right] \\ &= \inf_{M_{+}} \left[\int c d\pi + \sup_{\varphi, \psi} \left[\int \varphi d\mu + \int \psi d\nu - \int (\varphi + \psi) d\pi \right] \right] \\ &= \inf_{M_{+} \varphi, \psi} \left[\int \varphi d\mu + \int \psi d\nu - \int (\varphi(x) + \psi(y) - c(x, y)) d\pi \right] \\ &= \overset{MinMax}{\sup_{\varphi, \psi}} \left[\int \varphi d\mu + \int \psi d\nu - \sup_{M_{+}} \int (\varphi(x) + \psi(y) - c(x, y)) d\pi \right] \\ &= \sup_{\varphi, \psi, \varphi(x) + \psi(y) \leq c(x, y)} \left[\int \varphi d\mu + \int \psi d\nu \right] \end{split}$$

•	-	-	-	

4 Brenier's Theorem

4.1 Review of duality

 $\mu,\nu\in\mathbb{R}^d,\,c:\mathbb{R}^d\times\mathbb{R}^d\to[0,\infty].$

$$I(\pi) = \int c(x, y) d\pi$$

$$\inf_{\pi \in \Pi(\rho_0,\rho_1)} I(\pi) = \sup_{\Phi} J(\phi,\psi) = \sup_{\Phi} \int \varphi(x) d\mu(x) + \int \psi(y) d\nu(y)$$

Here, $\varphi(x) + \psi(y) \leq c(x, y), \forall x, y.$ $c(x, y) = \frac{1}{2} ||y - x||^2$

$$\inf_{\Pi(\mu,\nu)} I(\pi) = \frac{1}{2} W_2^2(\mu,\nu)$$

Duality takes form that

$$\sup_{\pi} \int \langle x, y \rangle \, d\pi(x, y) = \inf_{cx, lsc} \left[\int f(x) \mu(dx) + \int f^*(y) \nu(dy) \right]$$

For

$$\frac{1}{2}W_w^2(\mu,\nu) = \sup_{cx,lsc} \left[\int (\frac{1}{2}||x||^2 - f(x))\mu(dx) + \int \left(\frac{1}{2}||y||^2 - f^*(y)\right)\nu(dy) \right]$$

Transformed functions

$$\phi(x) = \frac{1}{2} ||x||^2 - f(x)$$

$$\phi^*(y) = \frac{1}{2} ||y||^2 - f^*(x)$$

These functions are c-concave functions and its dual. A pair of dual c-concave.

4.2 Brenier's Theorem

Theorem 4.1. Let μ, ν be two probability measures with finite second moments. Then, $\exists (f, f^*)$ a pair of cx, lsc function such that

$$\sup_{\Pi(x,y)} \int \langle x,y \rangle \, d\pi(x,y) = \int f(x)\mu(dx) + \int f^*(x)\nu(dy)$$

Theorem 4.2. (Breniers' 87) Suppose μ is absolutely continuous. Then,

- 1. There is a unique optimal coupling π of the Monge-Kantorovich OT problem given by $(X, \nabla f(X)), X \sim \mu$. Here, ∇f is the unique (uniquely determined μ almost everywhere) gradient of a convex function f such that ∇f pushforwards μ to ν . This function f also attains the maximum in the duality (in Thm. 4.1).
- 2. ∇f is the unique solution to the Monge problem

$$\int ||x - \nabla f(x)||^2 \mu(dx) = \min_{T \neq \mu = \nu} \int ||x - T(x)||^2 \mu(dx)$$

3. Suppose ν is also absolutely continuous. Then, for μ a.e. x and ν a.e. y,

$$\nabla f \circ \nabla f^*(y) = y, \nabla f^* \circ \nabla f(x) = x$$

Here, ∇f^* is the unique solution to the OT problem transporting μ to ν .

Proof. We already know there is an optimal coupling π , Duality,

$$\int \langle x, y \rangle \, d\pi^* = \sup_{\Pi(\mu,\nu)} \int \langle x, y \rangle \, d\pi =^{duality} \int f(x)\mu(dx) + \int f^*(y)\nu(dy)$$
$$\int (f(x) + f^*(y) - \langle x, y \rangle) d\pi^*(x,y) = 0$$

Thus, π^* a.e. (x, y), we have

$$f(x) + f^*(y) = \langle x, y \rangle$$

Further, we must have $y = \nabla(x), \forall \mu \ a.e. \ x$. Thus,

$$\pi^* = Law (x, \nabla f(x)), \text{ for } f \text{ that attains max in duality.}$$

This argument is showing that any optimal coupling is given by $\nabla f(x)$, where f attains duality.

Suppose, you found some f such that ∇f pushforward μ to ν . Can you claim the optimal coupling $\pi^* = {}^{Law}(x, \nabla f(x))$.

Benefit of duality.

Define $\pi = Law \ of \ (X, \nabla f(x)).$

$$\int \langle x, y \rangle \, d\pi = \int \langle x, \nabla f(x) \rangle \, d\mu$$
$$= \int f(x) d\mu + \int f^*(y) d\nu$$

$$\sup_{\Pi(\mu,\nu)} \int \langle x,y \rangle \, d\pi = \int \langle x,y \rangle \, d\pi = \int f(x) d\mu + \int f^*(y) d\nu = \inf\left[\int g(x) d\mu + \int g^* d\nu\right]$$

Uniqueness in both LHS/RHS.

We have already argues that any optimal π^* must be given by ∇f , for some cx, lsc function f.

Suppose (f,f^\ast) and (g,g^\ast) are two pairs of cx, lsc functions that give optimal couplings.

Proof. Call $(f, f^*) = \pi^*$.

$$\int \langle x, \nabla f(x) \rangle \, d\mu(x) = \int \langle x, y \rangle \, d\pi^* = \int \left(g(x) + g^*(y) \right) \, d\pi^*(x, y)$$

Because $\pi^* = (X, \nabla f(X)),$

$$\int \langle x, \nabla f(x) \rangle \, d\mu(x) = \int \langle x, y \rangle \, d\pi^* = \int \left(g(x) + g^*(y) \right) d\pi^*(x, y) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu(x) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu(x) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu(x) d\mu(x) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu(x) d\mu(x) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu(x) d\mu(x) d\mu(x) = \int \left(g(x) + g^*(\nabla f(x)) \right) d\mu(x) d\mu($$

Thus,

$$\int (g(x) + g^*(\nabla f(x))) - \langle x, \nabla f(x) \rangle) \mu(dx) = 0$$

Thus,

$$g(x) + g^*(\nabla f(x)) - \langle x, \nabla f(x) \rangle = 0, \ \mu \ a.e.$$

Thus,

$$\nabla f(x) = \nabla g(x), \mu \ a.e. \ x.$$

Uniqueness!

Solving OT for quadratic cost is equivalent looking for an optimal convex, lsc function.

Theorem 4.3. Let φ be a cx, lsc function, and let π be a coupling of μ, ν s.t.

$$\int (\varphi(x) + \varphi^*(y) - \langle x, y \rangle) d\pi(x, y) \le \epsilon$$

Then,

$$I(\pi) \le \left(\inf_{\Pi} I\right) + \epsilon = \frac{1}{2}W_2^2(\mu, \nu) + \epsilon$$

4.3 Cyclical monotonicity

Suppose we have discrete distributions that

$$\mu = \frac{1}{N} \sum_{i=1}^{N} \delta_{X_i}, \nu = \frac{1}{N} \sum_{i=1}^{N} \delta_{y_j}$$
$$\{x_1, \dots, x_N\}, \qquad \{y_1, \dots, y_N\}$$

Optimal matching problem. Double stochastic matrices

$$\min_{\Pi(\mu,\nu)} \int ||y-x||^2 d\pi = \min_{\sigma \in S_N} \frac{1}{N} \sum_{i=1}^N ||x_i - y_{\sigma_i}||^2$$

S_N is permutation of {1, 2, ..., N}

Question: Can one characterize the set of permutations where the minimum is achieved?

WLOG, assume the identity permutation is optimal.

$$\sum_{i=1}^{N} ||x_i - y_i||^2 \le \sum_{i=1}^{N} ||x_i - y_{\sigma_i}||^2, \forall \sigma \in S_N.$$

Consider permutation containing a single non-trivil cycle. One non-trivil cycle, others are identity (single cycle).

$$\begin{bmatrix} 11 \ 10 \ 5 \ 2 \ 1 \end{bmatrix} \begin{bmatrix} 3 \ 3 \end{bmatrix} \begin{bmatrix} 4 \ 4 \end{bmatrix} \begin{bmatrix} 6 \ 6 \end{bmatrix}$$
$$\begin{bmatrix} i_1 \ i_2 \ i_3 \dots i_m \end{bmatrix} \begin{bmatrix} 3 \ 3 \end{bmatrix} \begin{bmatrix} 4 \ 4 \end{bmatrix} \begin{bmatrix} 6 \ 6 \end{bmatrix}$$

Identity elsewhere. To be optimal, we must have

$$\sum_{l=1}^{m} ||x_{i_L} - y_{i_L}||^2 \le \sum_{l=1}^{m} ||x_{i_L} - y_{i_{L-1}}||^2$$

Definition 4.4. A Set of points $\{(x_1, y_1), ..., (x_N, y_N)\}$ is called cyclically monotone if for all $m \ge 1$, and all cycles $i_1 \leftarrow i_2 \leftarrow i_3 \leftarrow ... \leftarrow i_m$, the following holds.

$$\sum_{l=1}^{m} ||x_{i_L} - y_{i_L}||^2 \le \sum_{l=1}^{m} ||x_{i_L} - y_{i_{L-1}}||^2$$

Theorem 4.5. Identity is the optimal permutation if and only if $\{(x_1, y_1), ..., (x_n, y_n)\}$ is cyclically monotone.

Proof. Every permutation can be decomposed as union of disjoint cycles. If

$$\sum ||x_i - y_i|| \le \sum ||x_i - y_{\sigma_i}||^2$$

Definition 4.6. A subset $\Gamma \subseteq \mathbb{R}^d \times \mathbb{R}^d$ is called cyclically monotone if for any collection of $\{(x_1, y_1), ..., (x_m, y_m)\} \subseteq \Gamma$,

$$\sum ||x_i - y_i||^2 \le \sum_{i=1}^m ||x_i - y_{i-1}||^2$$

Theorem 4.7. Any optimal coupling π^* of MK OT problem, must be concentrated ($\exists \Gamma \subseteq \mathbb{R}^d \times \mathbb{R}^d$, cyclically monotone, $\pi^*(\Gamma) = 1$) on a cyclically monotone set.

Proof. Want to couple μ to ν .

We will sample $X_1, ..., X_N \sim \mu, y_1, ..., y_N \sim \nu$. Match these optimally. Have

$$\pi_N^* \to_{N \to \infty} \pi^*$$

from support

$$\Gamma_N \to I$$

4.4 Connect Brenier Theorem to Cyclically monotonicity

If we have μ abs. cont., if we have ν

$$\pi^* = ^{Law} (X, \nabla f(X)), x \sim \mu$$

$$\Gamma = \left\{ \left(x, \nabla f(x) \right), x \in \mathbb{R}^d \right\}$$

Rockafeller's Theorem.

If Γ is cyclically monotone, Conversely, any maximumally cyclically monotone subset, must be given by $\{(x, \partial f(x)), x \in \mathbb{R}^d\}$.

5 Lecture 5

5.1 Review Brenier's Theorem

Example 5.1. \mathbb{R}^d , and we have $\mu = \mathcal{N}(a_1, \Sigma_1), \nu = \mathcal{N}(a_2, \Sigma_2)$. What is the optimal MK map between them?

Consider the map $T : \mathbb{R}^d \to \mathbb{R}^d$,

$$T(x) = a_2 + A(x - a_1), A = \Sigma_1^{-1/2} (\Sigma_1^{1/2} \Sigma_2 \Sigma_1^{1/2})^{1/2} \Sigma_1^{-1/2}$$

We can know A is symmetric and PD. If $X \sim \mathcal{N}(a_1, \Sigma_1)$, then $y = T(x) \sim \mathcal{N}(\cdot, \cdot)$.

$$\mathbb{E}[y] = a_2 + \mathbb{E}[A(x - a_1)] = a_2$$

We know

$$\begin{split} \Sigma_y &= A \Sigma_1 A = \Sigma_1^{-1/2} (\Sigma_1^{1/2} \Sigma_2 \Sigma_1^{1/2})^{1/2} \Sigma_1^{-1/2} \Sigma_1 \Sigma_1^{-1/2} (\Sigma_1^{1/2} \Sigma_2 \Sigma_1^{1/2})^{1/2} \Sigma_1^{-1/2} \\ &= \Sigma_2 \end{split}$$

How do we know this is a gradient of a convex function? Define

$$f(x) = \langle a_2, x \rangle + \frac{1}{2} \langle (x - a_1), A(x - a_1) \rangle$$

= $a_2^T x + \frac{1}{2} (x - a_1)^T A(x - a_1)$

Then

$$\nabla f(x) = a_2 + A(x - a_1) = T(x)$$

Since f(x), A is PD, we know f(x) is convex. Then, T(x) is the optimal map.

$$W_2^2(\mu,\nu) = \mathbb{E}_{\mu}||T(x) - x||^2 = \mathbb{E}||a_2 + A(x - a_1) - x||^2 = ||a_2 - a_1||^2 + tr(\Sigma_z)$$

Consider

$$z = T(x) - x = a_2 + A(x - a_1) - x \sim \mathcal{N}[a_2 - a_1, \Sigma_z] = a_2 - Aa_1 + (A - I)x$$

$$\Sigma_z = (A - I)\Sigma_1(A - I)$$

= $\Sigma_1 + \Sigma_2 - 2(\Sigma_1^{1/2}\Sigma_2\Sigma_1^{1/2})^{1/2}$

$$W_2^2(\mu,\nu) = ||a_2 - a_1||^2 + Tr\left[\Sigma_1 + \Sigma_2 - 2(\Sigma_1^{1/2}\Sigma_2\Sigma_1^{1/2})^{1/2}\right]$$

If $a_1 = a_2$,

$$W_2^2(\mu,\nu) = Tr\left[\Sigma_1 + \Sigma_2 - 2(\Sigma_1^{1/2}\Sigma_2\Sigma_1^{1/2})^{1/2}\right]$$

Bures metric square on PSD matrices. If $\Sigma_1 \Sigma_2 = \Sigma_2 \Sigma_1$, then

$$W_2^2(\mu,\nu) = ||a_1 - a_2||^2 + Tr\left[(\Sigma_1^{1/2} - \Sigma_1^{1/2})^2\right]$$

If $\Sigma_1 = \Sigma_2$, then

$$W_2^2(\mu,\nu) = ||a_1 - a_2||^2$$

Example 5.2. Let $\mu \sim Unif(D), D = \{(x, y) : x^2 + y^2 \le 1\}$. Let $\nu \sim Unif(U), U = \{(x, y) : x^2 + y^2 = 1\}$. A natural guess is to do

$$T(x) = \frac{x}{||x||}$$

How do I verify T is optimal? Consider

$$f(x) = ||x|$$

$$\nabla f(x) = \frac{x}{||x||}$$

Thus, T is optimal for the quadratic cost.

Example 5.3. Take unit square, take μ - Uniform distribution over $[0, 1]^2$. And ν = discrete uniform over $\{(0, 0), (1, 1), (1, 0), (0, 1)\}$.

Optimal map for transporting μ to ν ? Another natural guess is to

$$T(x) = (1(x > 1/2), 1(y > 1/2))$$

Convex function

$$f(x) = (x - 1/2)^{+} + (y - 1/2)^{+}$$
$$z^{+} = max(z, 0)$$

Twist,

$$c(x,y) = -||y - x||^2$$

5.2 Optimal transport in 1-dimension

 $X \sim \mu, y \sim \nu$ on \mathbb{R} . Find OT from μ to ν for $c(x, y) = ||y - x||^2$. Cumulative distribution function (CDF).

$$F_{\mu}(t) = P(x \le t)$$

 F_{μ} is non-decreasing and

$$\lim_{t \to -\infty} F_{\mu}(t) = 0$$
$$\lim_{t \to \infty} F_{\mu}(t) = 1$$

May not be continuous. Similarly, we could define $F_{\nu}(t)$.

Lemma 5.4. Suppose μ is abs. cont. Then define $U = F_{\mu}(x)$. Then, $U \sim Unif(0,1)$.

Definition 5.5. Define inverse CDF that

$$F_{\mu}^{-1}(t) = \inf \{ x : F_{\mu}(x) \ge t \}$$

Corollary 5.6. We have

$$\{t \le F_{\mu}(x)\} = \{F_{\mu}^{-1}(t) \le x\}$$

Proof. Pick $0 \le t \le 1$,

$$P(U \ge t) = P_{\mu} \left(F_{\mu}(x) \ge t \right) = P_{\mu}(x \ge F_{\mu}^{-1}(t)) = 1 - t$$

Lemma 5.7. [Inverse Sampling] Suppose $U \sim Unif(0,1)$. Then, $y = F_{\nu}^{-1}(U)$. Then, $y \sim \nu$.

Proof. We have

$$P(Y \le y) = P(F_{\nu}^{-1}(U) \le y) = P(U \le F_{\nu}(y)) = F_{\nu}(y)$$

$$X \to_{F_{\mu}} U \to_{F_{\nu}^{-1}} y$$

If we have $X \sim \mu$, and

$$F_{\nu}^{-1} \circ F_{\nu}(x) \sim \nu$$

If we take $T(x) = F_{\nu}^{-1} \circ F_{\mu}(x)$. Then, $T(x) = \nabla f(x), \exists f \ c.x.$ T is an increasing function. Thus, define

$$f(x) = \int_0^x T(y) dy$$

then f is convex.

In 1-d, increasing function \iff derivative of a convex function. Brenier's Theorem $\iff T(x)$ is the OT map for quadratic cost.

5.2.1 Natural

Suppose F is strictly increasing. F^{-1} is a well-defined strictly increasing map. If we take 0 ,

$$F^{-1}(p) = pth \ quantile$$

 $F^{-1}(1/2) = median$
 $F^{-1}(1/2) = 1st \ quantile$

 $x\mapsto T(x)$ Monotone rearrangements (quantile-quantile maps). Here,

 $\mu 1 {\rm st}$ quantile, median, pth quantile $\mapsto \nu 1 {\rm st}$ quantile, median, pth quantile In 1-d, quadratic cost is not special.

$$c(x,y) = h(x-y), h \ strict \ cx.$$

Then, optimal map is monotone rearrangement.

$$c(x,y) = -h(x-y), h \text{ strict concave.}$$

Optimal map is anti-monotone.

$$F^{-1}_{\mu}(p) \longleftrightarrow F^{-1}_{\nu}(1-p)$$

Example 5.8. $\mu = \frac{1}{2}Unif(0,1) + \frac{1}{2}Unif(3,4)$. $\nu = Unif(3,5)$.

We could clearly see the monotone transform map as optimal transport map.

$$T(x) = \begin{cases} x+3, & if \ 0 \le x \le 1\\ x+1, & if \ 3 \le x \le 4 \end{cases}$$

5.3 Knothe-Rosenblatt Transport (KR map)

f, g are densities on \mathbb{R}^d . $x = (x_1, ..., x_d) \sim f$, $y = (y_1, ..., y_d) \sim g$.

$$f(x_1, \dots, x_d) = f_1(x_1) f_{2|1}(x_2|x_1) f_{3|2,1}(x_3|x_2, x_1) \dots f_{d|d-1,\dots,1}(x_d|x_{d-1}, \dots, x_1)$$

 $g(y_1, ..., y_d) = g_1(y_1)g_{2|1}(y_2|y_1)g_{3|2,1}(y_3|y_2, y_1) \dots g_{d|d-1,...,1}(y_d|y_{d-1}, ..., y_1)$ Let T_1 be the monotone map from $f_1 \to g_1$

 $x_1 \sim f_1$

$$y_1 = T(x_1) \sim g_1$$

 $\begin{aligned} x_1 &= x_1, \ y_1 = T(x_1) = y_1. \\ T_{2|x_1} \text{ monotone map from } f_{2|1}(\cdot|x_1) \to g_{2|1}(\cdot|y_1 = T(x_1)). \end{aligned}$

$$y_2 = T_{2|x_1}(x_2)$$

$$(y_1, y_2) \sim g_1(y)g_{2|1}(y_2|y_1)$$

Inductively, given $x_1, ..., x_{k-1}$ and $y_1, ..., y_{k-1}$. $T_{k|x_{k-1},...,x_1}$ monotone map $f_{k|k-1,...,1}(\cdot|x_{k-1},...,x_1) \to g_{k|k-1,...,1}(\cdot|y_{k-1},...,y_1)$. This defines $(x_1, ..., x_d) \mapsto (y_1, ..., y_d)$. KR-map.

- 1. Need to know inverses of all conditional.
- 2. KR map is traingular. To generate y_k , I only need to know $x_1, ..., x_k$.
- 3. Train neural network to produce an estimate.
- 4. The order in which $x_1, ..., x_d$ appears matter. d! KR map.
- 5. No optimality. However,

Consider $c_{\epsilon}(x, y) = \sum_{i=1}^{d} \lambda_i(\epsilon)(x_i - y_i)^2$ a weighted quadratic cost. $\lambda_i(\epsilon) > 0.$ Take f, g, OT w.r.t. e_{ϵ} . T_{ϵ}

Theorem 5.9. Suppose k = 1, 2, ..., d - 1

$$\lim_{\epsilon \to 0^+} \frac{\lambda_{k+1}(\epsilon)}{\lambda_k(\epsilon)} = 0$$

Then, $T_{\epsilon} \rightarrow_{L^2(f)} T(KR \ map)$.

Dynamical Optimal Transport $\mathbf{5.4}$

 $\begin{array}{l} \rho_{1},\rho^{'} \text{ densities on } \mathbb{R}^{d}.\\ \text{ We have a Brenier map } x\sim\rho,\,\nabla\psi(x)\sim\rho^{'}.\ \psi \text{ cx Brenier map.} \end{array}$

$$x_t = (1-t)x + t\nabla\psi(x)$$

Call this $T_t(x) = (1-t)x + t\nabla\psi(x)$. $X \sim \rho$,

$$\rho_t =^{Law} x_t \iff \rho_t = T_{t_\#} \rho$$

Definition 5.10. (McCann's displacement interpolation)

$$(\rho_t, 0 \le t \le 1)$$

is called the displacement interpolation between ρ and ρ' .

Example 5.11. $\rho \sim \mathcal{N}(0, I), \, \rho' \sim \mathcal{N}(a, I).$

$$x \mapsto T(x) = x + a$$

$$X_t = (1-t)x + t(x+a) = x + ta$$

$$\begin{split} X_t \sim \mathcal{N}(ta,I) &= \rho_t \\ \textbf{Example 5.12.} \ \rho \sim Unif(0,1)^d, \ \rho^{'} \sim Unif[0,r]^d. \\ \rho_t \sim [0,1-t+tr]^d \\ T(x) &= rx = \nabla(\frac{1}{2}r||x||^2) \end{split}$$

$$X_t = (1 - t)X + trX$$
$$= (1 - t + tr)X$$

Law of $X_t = Unif[0, 1 - t + tr]^d = \rho_t$.